

PENTOR – 5-axis system

The PENTOR was developed to perform a linear movement in three axes while being able to provide tip and tilt motion. This piezo electric stage grants in total 5 degrees of freedom and thus provides a high spatial positioning flexibility to fulfill complex tasks.

A linear stroke of 100 μm is accessible in all three axes X, Y and Z. The tilt motion of ± 2 mrad can be performed around the X and Y axis, respectively. In addition, the PENTOR is equipped with a 17mm diameter open aperture that makes it ideal for optical setups. Due to high resonant frequencies of all axes, it is also well suited for dynamic applications.

The 5-axes piezo stage is available in open and closed loop versions. The latter one is equipped with strain gage sensors to overcome drift and hysteresis. Vacuum and low temperature versions are available upon request as well.

We recommend to use the digital controller d-Drive (E-751-000) in combination with 5 EVD50(CL) modules for driving the PENTOR in order to take full benefit of the precise mechanics and the low noise electronics to get the best performance.



PENTOR 100 SG

Product highlights:

- combination of a three axis translation system and a two axis tilting system
- free center hole with 17 mm diameter
- integrated preload
- translation each axis: 100 μm
- tilt each direction: ± 2 mrad
- solid state flexure hinges in parallelogram design without mechanical play
- optional measurement system
- vacuum and low temperature versions available

Application examples:

- scanning system
- micro and nano positioning
- dynamical applications
- laser tuning

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Technical Data

PENTOR series part number	unit	PENTOR T-450-00	PENTOR SG T-450-01	PENTOR SG T-450-01D	
axes	-	x, y, z, Θ_x , Θ_y			
voltage range	V	-20 ... +130			
central aperture	mm	17			
max. load	N	50			
temperature range	°C	-20 ... +80 (-4°F ... 176°F)			
dimensions (length, width, height)	mm	69 x 68 x 40 (2.7" x 2.7" x 1.6")			
weight	g	450 (0.99 lbs)	480 (1.06 lbs)		
PENTOR translation stage					
motion ($\pm 10\%$) x,y,z open loop	μm	100			
motion ($\pm 0.2\%$) x,y,z closed loop	μm	-	80		
resolution	open loop	nm	0,2		
	closed loop	nm	-	2	
capacitance (per axis) $\pm 20\%$	μF	1,7			
resonant frequency (unloaded)	x-axis	Hz	680		
	y-axis	Hz	750		
	z-axis	Hz	580		
stiffness (per axis)	N/ μm	0,5			
typ. non-linearity	%	-	x: 0.05, y: 0.06, z: 0.02		
typ. repeatability	nm	-	x: 5, y: 4, z: 5		
PENTOR tilting stage					
tilt ($\pm 10\%$) Θ_x, Θ_y	open loop	mrad	± 2		
tilt ($\pm 0.2\%$) Θ_x, Θ_y	closed loop	mrad	-	$\pm 1,6$	
resolution	open loop	μrad	0.008	0.008	0.008
	closed loop	μrad	-	0.08	0.08
voltage range	V	-20 ... +130			
number of axes	-	2			
capacitance (per axis) $\pm 20\%$	μF	2 x 0,85			
typ. non-linearity	%	-	Θ_x : 0.18, Θ_y : 0.13		
typ. repeatability	μrad	-	Θ_x : 0.44, Θ_y : 0.48		